

0945030-03101

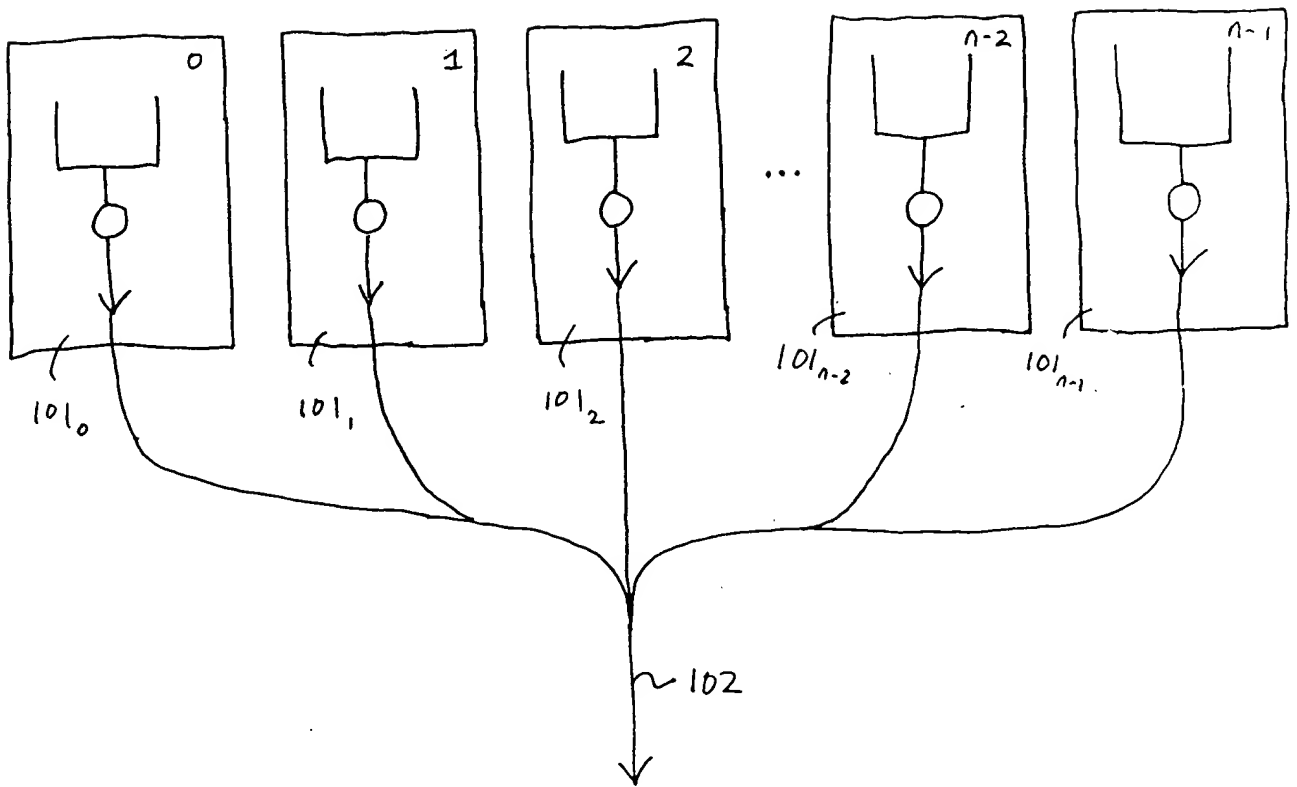


FIGURE 1

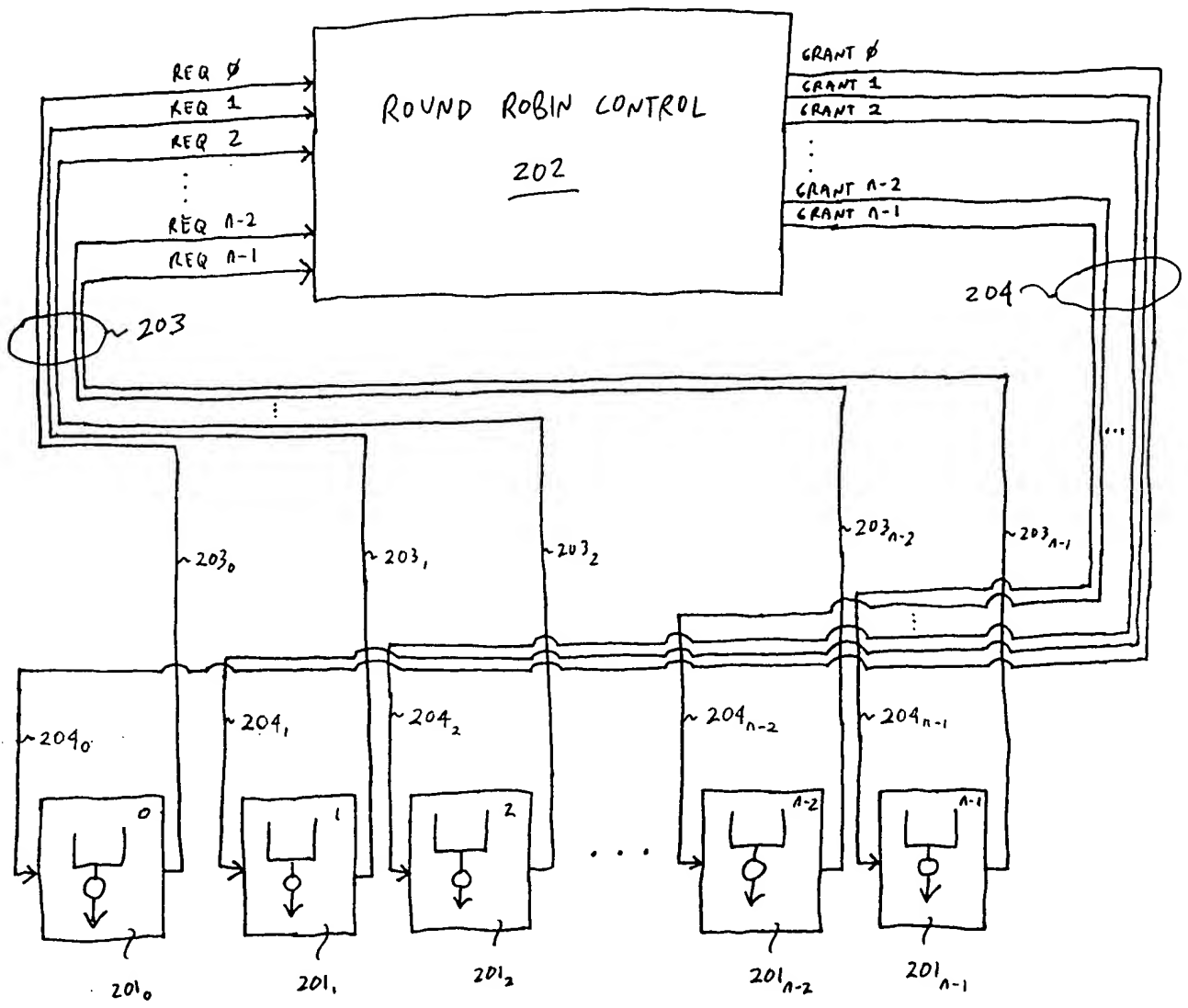


FIGURE 2

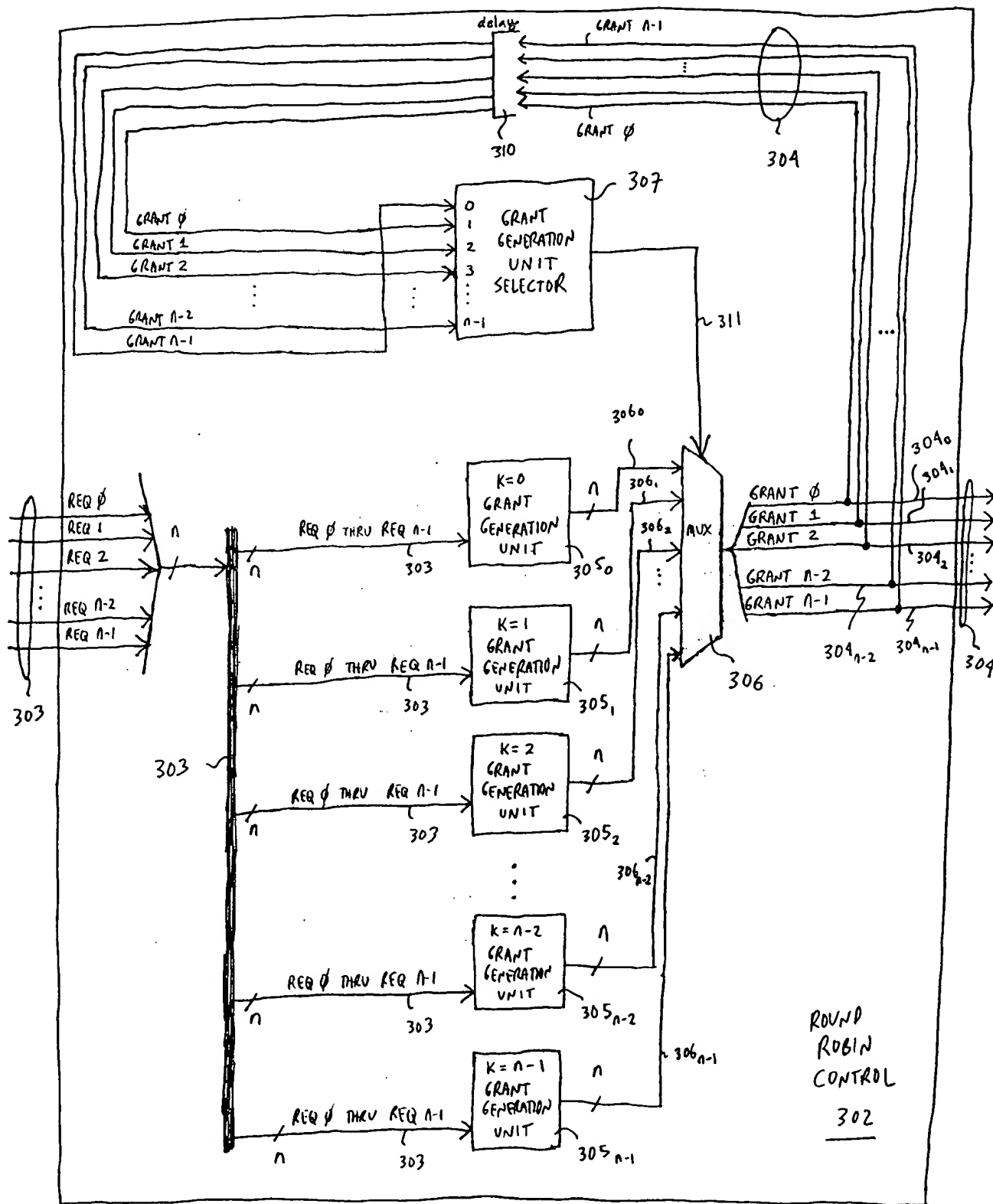


FIGURE 3a

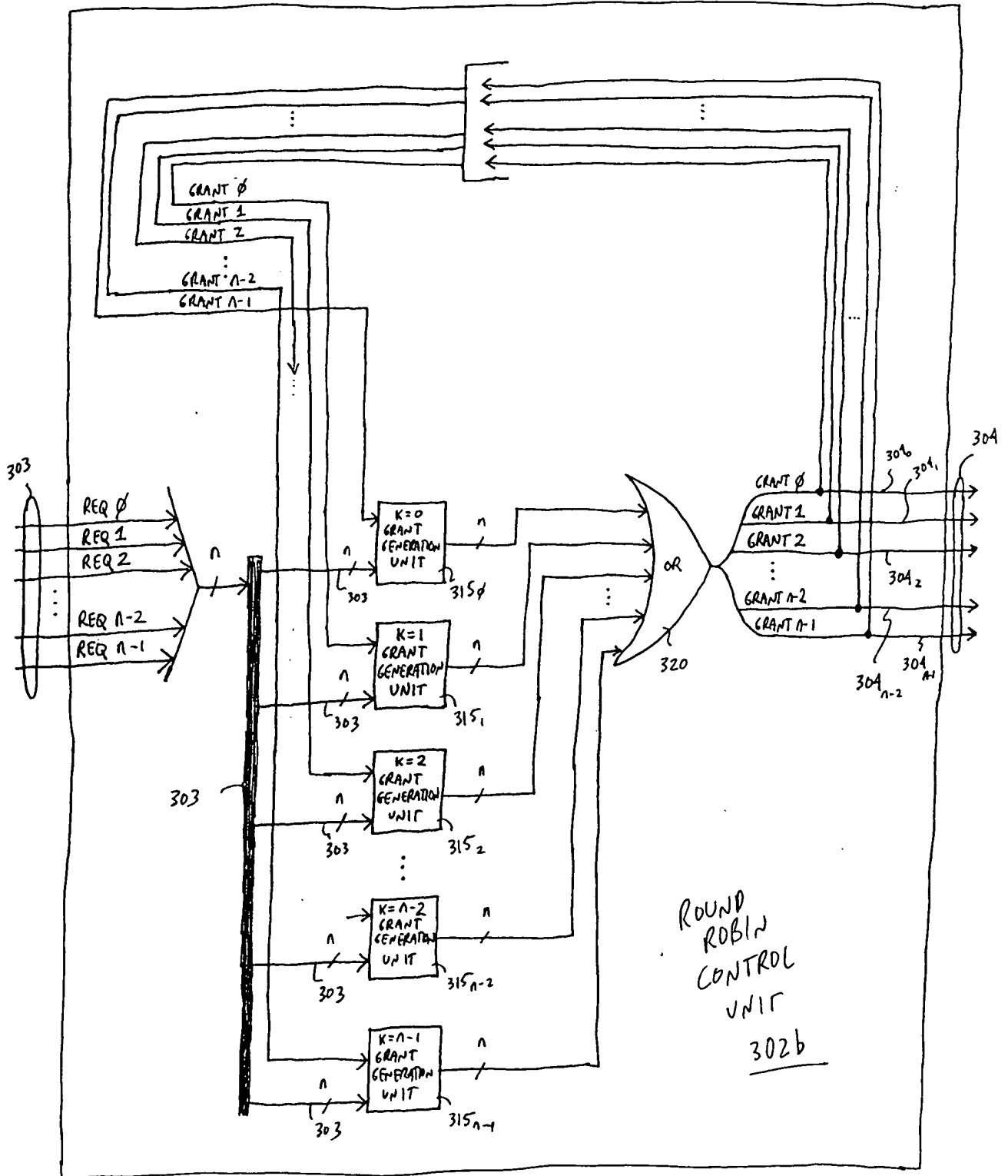


FIGURE 3b

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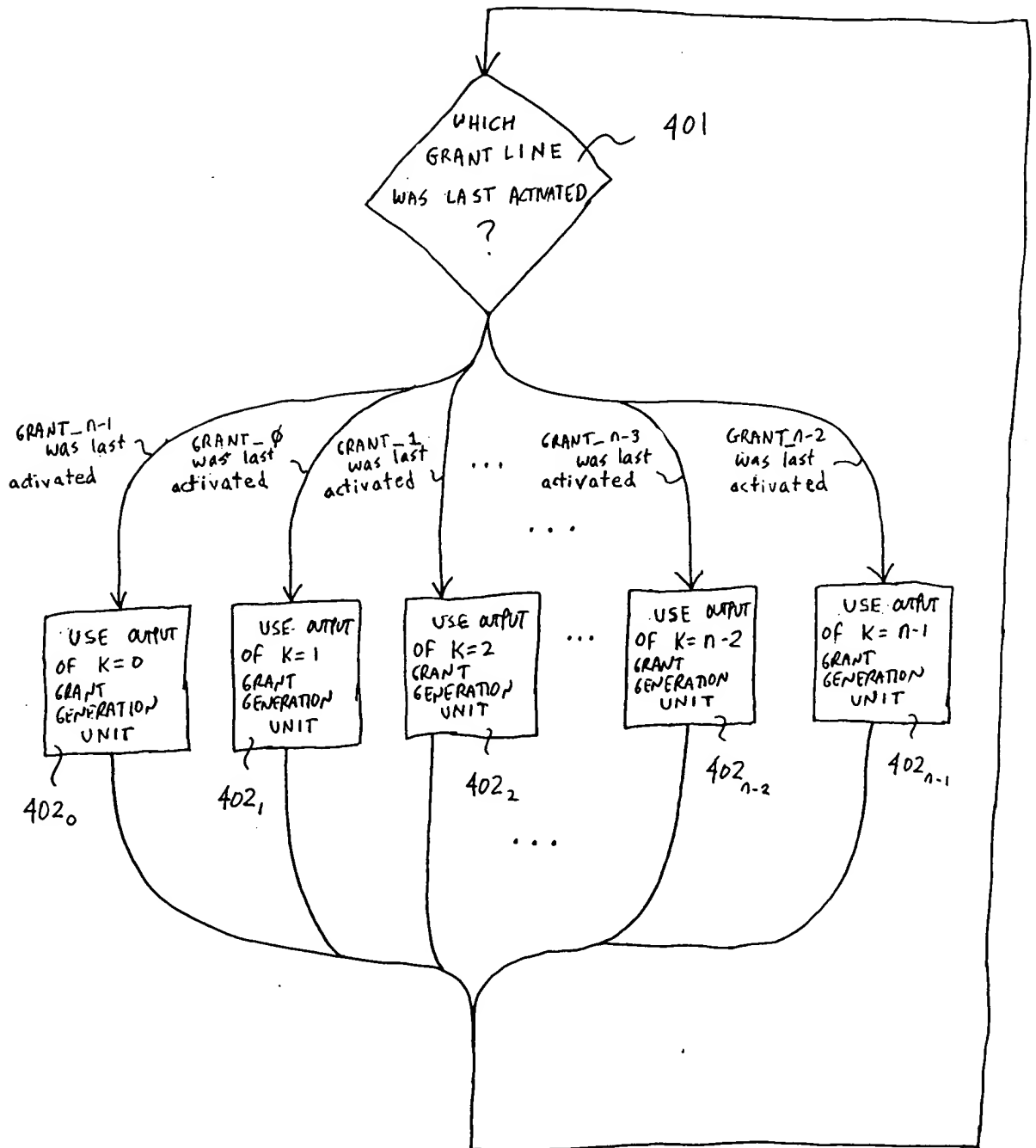


FIGURE 4

400

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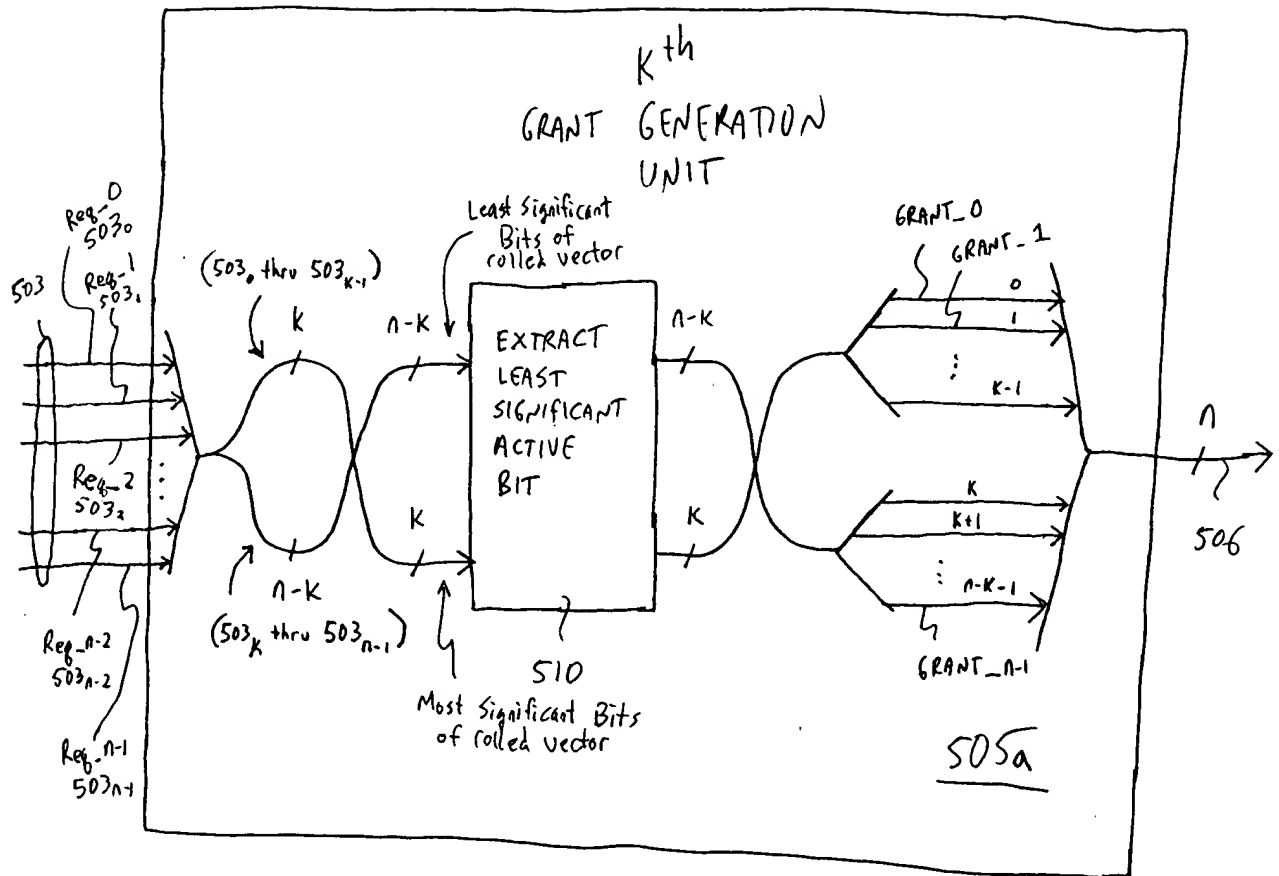


FIGURE 5a

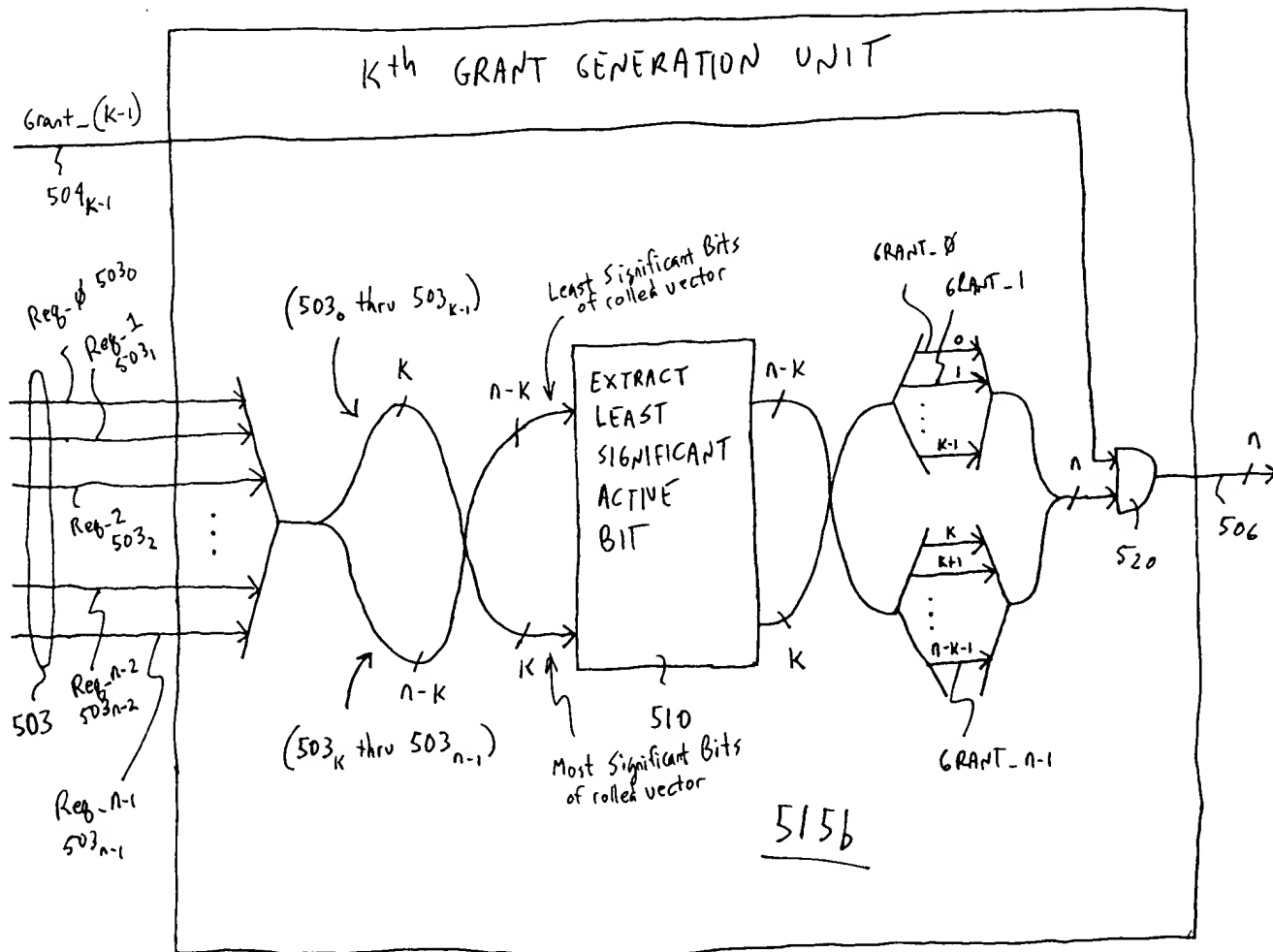


FIGURE 5b

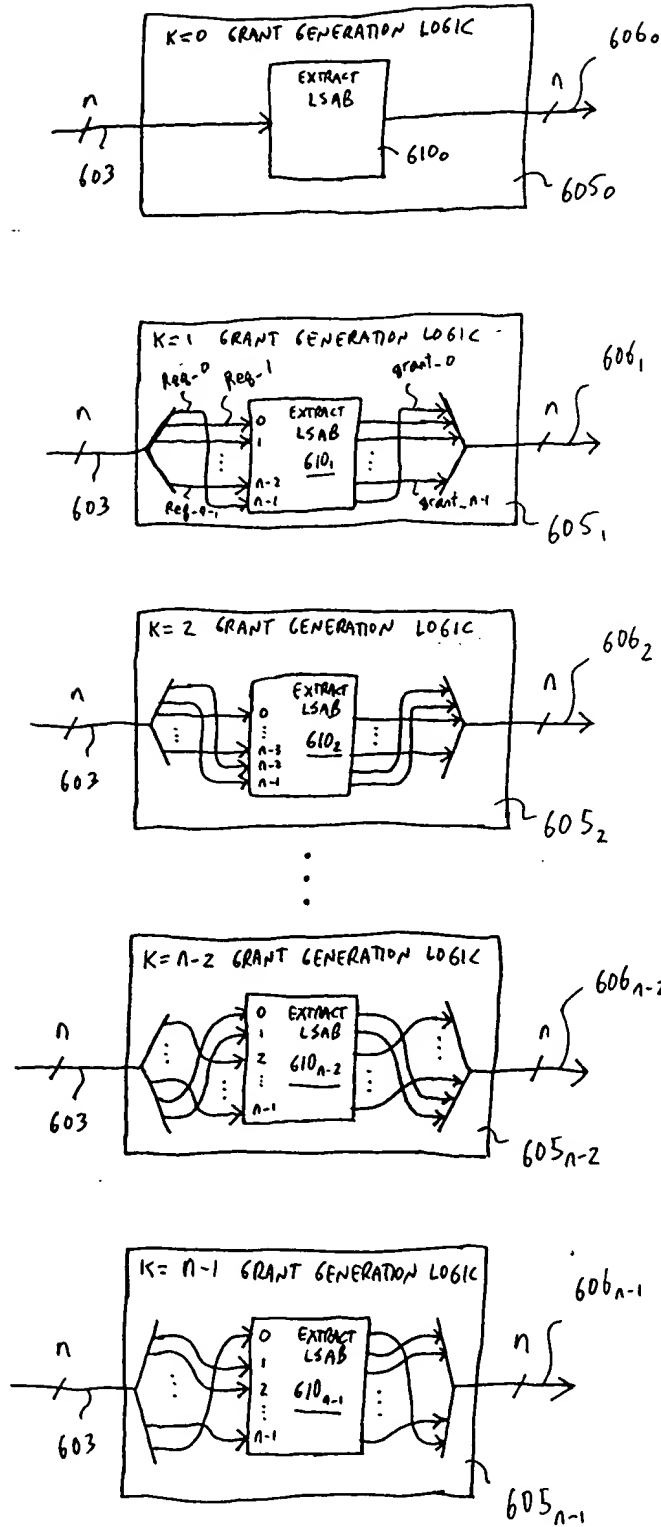


FIGURE 6

ASIC Patent proposal
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```

module rr (dataIn, state, dataOut) /* synthesis syn_hier = "flatten,remove" */;

input [19:0] dataIn;
input [19:0] state;
output [19:0] dataOut;

wire [19:0] dataOut0, dataOut1, dataOut2, dataOut3, dataOut4,
dataOut5, dataOut6, dataOut7, dataOut8, dataOut9,
dataOut10, dataOut11, dataOut12, dataOut13, dataOut14,
dataOut15, dataOut16, dataOut17, dataOut18, dataOut19;

prio prio0 (.dataIn(dataIn), .en(state[19]),
.dataOut(dataOut0));

prio prio1 (.dataIn({dataIn[0], dataIn[19:1]}), .en(state[0]),
.dataOut({dataOut1[0], dataOut1[19:1]}));

prio prio2 (.dataIn({dataIn[1:0], dataIn[19:2]}), .en(state[1]),
.dataOut({dataOut2[1:0], dataOut2[19:2]}));

prio prio3 (.dataIn({dataIn[2:0], dataIn[19:3]}), .en(state[2]),
.dataOut({dataOut3[2:0], dataOut3[19:3]}));

prio prio4 (.dataIn({dataIn[3:0], dataIn[19:4]}), .en(state[3]),
.dataOut({dataOut4[3:0], dataOut4[19:4]}));

prio prio5 (.dataIn({dataIn[4:0], dataIn[19:5]}), .en(state[4]),
.dataOut({dataOut5[4:0], dataOut5[19:5]}));

prio prio6 (.dataIn({dataIn[5:0], dataIn[19:6]}), .en(state[5]),
.dataOut({dataOut6[5:0], dataOut6[19:6]}));

prio prio7 (.dataIn({dataIn[6:0], dataIn[19:7]}), .en(state[6]),
.dataOut({dataOut7[6:0], dataOut7[19:7]}));

prio prio8 (.dataIn({dataIn[7:0], dataIn[19:8]}), .en(state[7]),
.dataOut({dataOut8[7:0], dataOut8[19:8]}));

prio prio9 (.dataIn({dataIn[8:0], dataIn[19:9]}), .en(state[8]),
.dataOut({dataOut9[8:0], dataOut9[19:9]}));

prio prio10 (.dataIn({dataIn[9:0], dataIn[19:10]}), .en(state[9]),
.dataOut({dataOut10[9:0], dataOut10[19:10]}));

prio prio11 (.dataIn({dataIn[10:0], dataIn[19:11]}), .en(state[10]),
.dataOut({dataOut11[10:0], dataOut11[19:11]}));

prio prio12 (.dataIn({dataIn[11:0], dataIn[19:12]}), .en(state[11]),
.dataOut({dataOut12[11:0], dataOut12[19:12]}));

prio prio13 (.dataIn({dataIn[12:0], dataIn[19:13]}), .en(state[12]),
.dataOut({dataOut13[12:0], dataOut13[19:13]}));

prio prio14 (.dataIn({dataIn[13:0], dataIn[19:14]}), .en(state[13]),
.dataOut({dataOut14[13:0], dataOut14[19:14]}));

prio prio15 (.dataIn({dataIn[14:0], dataIn[19:15]}), .en(state[14]),
.dataOut({dataOut15[14:0], dataOut15[19:15]}));

prio prio16 (.dataIn({dataIn[15:0], dataIn[19:16]}), .en(state[15]),
.dataOut({dataOut16[15:0], dataOut16[19:16]}));

prio prio17 (.dataIn({dataIn[16:0], dataIn[19:17]}), .en(state[16]),
.dataOut({dataOut17[16:0], dataOut17[19:17]}));

prio prio18 (.dataIn({dataIn[17:0], dataIn[19:18]}), .en(state[17]),
.dataOut({dataOut18[17:0], dataOut18[19:18]}));

prio prio19 (.dataIn({dataIn[18:0], dataIn[19]}), .en(state[18]),
.dataOut({dataOut19[18:0], dataOut19[19]}));

assign dataOut = ((dataOut0 | dataOut1 | dataOut2 | dataOut3) |
(dataOut4 | dataOut5 | dataOut6 | dataOut7) |
(dataOut8 | dataOut9 | dataOut10 | dataOut11) |
(dataOut12 | dataOut13 | dataOut14 | dataOut15) |
(dataOut16 | dataOut17 | dataOut18 | dataOut19));

endmodule // rr

```

FIGURE 7

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703 →

Figure 4. The "round robin" top level Verilog module for N=20

6/26/01

7(9)

Company Confidential
Turin Networks, Inc.

TOP SECRET

ASIC Patent proposal
Alfa-Romeo

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```
module prio (dataIn, en, dataOut);
input [19:0] dataIn;
input en;
output [19:0] dataOut;

reg [19:0] i_dataOut0;
```

FIGURE 8

```
always @(*AUTONSENSE*/dataIn) begin
    i_dataOut0 = 20'd0;
    if (dataIn[0]) i_dataOut0 = 20'h00001;
    else if (dataIn[1]) i_dataOut0 = 20'h00002;
    else if (dataIn[2]) i_dataOut0 = 20'h00004;
    else if (dataIn[3]) i_dataOut0 = 20'h00008;
    else if (dataIn[4]) i_dataOut0 = 20'h00010;
    else if (dataIn[5]) i_dataOut0 = 20'h00020;
    else if (dataIn[6]) i_dataOut0 = 20'h00040;
    else if (dataIn[7]) i_dataOut0 = 20'h00080;
    else if (dataIn[8]) i_dataOut0 = 20'h00100;
    else if (dataIn[9]) i_dataOut0 = 20'h00200;
    else if (dataIn[10]) i_dataOut0 = 20'h00400;
    else if (dataIn[11]) i_dataOut0 = 20'h00800;
    else if (dataIn[12]) i_dataOut0 = 20'h01000;
    else if (dataIn[13]) i_dataOut0 = 20'h02000;
    else if (dataIn[14]) i_dataOut0 = 20'h04000;
    else if (dataIn[15]) i_dataOut0 = 20'h08000;
    else if (dataIn[16]) i_dataOut0 = 20'h10000;
    else if (dataIn[17]) i_dataOut0 = 20'h20000;
    else if (dataIn[18]) i_dataOut0 = 20'h40000;
    else if (dataIn[19]) i_dataOut0 = 20'h80000;
end

assign dataOut = {20{en}} & i_dataOut0;

endmodule // prio
```

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Figure 5. The basic "brute force" verilog implementation of the "prio" module for N=20. This generates the smallest area but is slower than the alternative implementation shown next.

ASIC Patent proposal
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```

module prio (dataIn, en, dataOut) /* synthesis syn_hier = "flatten,remove" */;
input [19:0] dataIn;
input en;
output [19:0] dataOut;

reg [4:0] i_dataOut0;
reg [4:0] i_dataOut1;
reg [4:0] i_dataOut2;
reg [4:0] i_dataOut3;
wire [9:0] i_dataOut4;
wire [9:0] i_dataOut5;

wire muxCtl1;
wire muxCtl2;
wire muxCtl3;

// Calc in parallel
assign muxCtl1 = dataIn[4:0];
assign muxCtl2 = dataIn[14:10];
assign muxCtl3 = dataIn[9:5] | muxCtl1;

always @(*AUTONSENSE*/dataIn) begin
    i_dataOut0 = 5'd0;
    if (dataIn[0]) i_dataOut0 = 5'h01;
    else if (dataIn[1]) i_dataOut0 = 5'h02;
    else if (dataIn[2]) i_dataOut0 = 5'h04;
    else if (dataIn[3]) i_dataOut0 = 5'h08;
    else if (dataIn[4]) i_dataOut0 = 5'h10;
end // always @ (...)

always @(*AUTONSENSE*/dataIn) begin
    i_dataOut1 = 5'd0;
    if (dataIn[5]) i_dataOut1 = 5'h01;
    else if (dataIn[6]) i_dataOut1 = 5'h02;
    else if (dataIn[7]) i_dataOut1 = 5'h04;
    else if (dataIn[8]) i_dataOut1 = 5'h08;
    else if (dataIn[9]) i_dataOut1 = 5'h10;
end // always @ (...)

always @(*AUTONSENSE*/dataIn) begin
    i_dataOut2 = 5'd0;
    if (dataIn[10]) i_dataOut2 = 5'h01;
    else if (dataIn[11]) i_dataOut2 = 5'h02;
    else if (dataIn[12]) i_dataOut2 = 5'h04;
    else if (dataIn[13]) i_dataOut2 = 5'h08;
    else if (dataIn[14]) i_dataOut2 = 5'h10;
end // always @ (...)

always @(*AUTONSENSE*/dataIn) begin
    i_dataOut3 = 5'd0;
    if (dataIn[15]) i_dataOut3 = 5'h01;
    else if (dataIn[16]) i_dataOut3 = 5'h02;
    else if (dataIn[17]) i_dataOut3 = 5'h04;
    else if (dataIn[18]) i_dataOut3 = 5'h08;
    else if (dataIn[19]) i_dataOut3 = 5'h10;
end // always @ (...)

// "Mux" data out
assign i_dataOut4 = {i_dataOut1 & {5{~muxCtl1}}, i_dataOut0 & {5{muxCtl1}}};
assign i_dataOut5 = {i_dataOut3 & {5{~muxCtl2}}, i_dataOut2 & {5{muxCtl2}}};
assign dataOut = {i_dataOut5 & {10{en & ~muxCtl3}}, i_dataOut4 & {10{en & muxCtl3}}};

endmodule // prio

```

FIGURE 9

Figure 6. Alternative "prio" module Verilog implementation.